Question Bank (G scheme)

Name of subject: BASIC ELECTRONICS & MECHATRONICS Unit Test :II Subject code : 17302 Course : ME

Semester: III 4 Marks Questions :

Chapter - IV

- 1. Write truth table for XOR and XNOR gate. Draw their symbols.
- 2. What is mulitiplexer. Draw logical symbol of 4:1 multiplexer.
- 3. Compare microprocessor and microcontroller.
- 4. What is flipflop ?List types of flip- flop and state its applications.
- 5. What is half adder? Draw logical circuit of half adder along with its truth table.
- 6. Sketch 4-bit asynchronous counter.

Chapter -V

- 1. With a suitable example explain the concept of primary and secondary transducer.
- 2. Explain the selection criteria for the transducer for any application.
- 3. Explain the operation of analog to digital convertor.
- 4. Draw and explain single channel data application system.
- 5. Give two examples each of Active and Passive Transducer.

Chapter -VI

- 1. List the advantages and disadvantages of Mechatronic system.
- 2. What is PLC? draw the block diagram and state applications of PLC.
- 3. Draw the block diagram of CNC machine and explain its operation.
- 4. State the features of real time mechatronics.
- 5. List criteria for selection of PLC for an application.
- 6. With the help of neat labeled diagram explain FMS.

3 Marks questions :

Chapter -IV

- 1. Define logic gate and truth table.
- 2. Draw symbol of AND, OR & NOT gates.
- 3. Write truth tables for AND, OR & NOT gates.
- 4. Draw symbol of S-R and J-K flip flop.
- 5. Write two diffrences between D flip flop and T flipflop.
- 6. Draw block diagram Microprocessor and Micro controller.

Chapter -V

- 1. What is tranducer? Classify.
- 2. State the meaning of ADC.
- 3. What is A.C. Signal Conditioning.
- 4. Draw block diagram of D.C signal conditioning system.
- 5. What is data logger. Give any four applications.
- 6. State the role of DAS in brief.

Chapter -VI

- 1. What is mechatronics. Write applications.
- 2. What are basic elements of mechatronics.
- 3. What is FMS? Give its advantages.
- 4. Define PLC.
- 5. State types of Robotics.